



**MICROWAVE SENSOR
FOR CRANE CRASH AVOIDANCE**

MWS-CAS-2A/B^{PAT.}

MICRO-ROBO

**Multi Channel type with
Received Power Level
Indicators.**



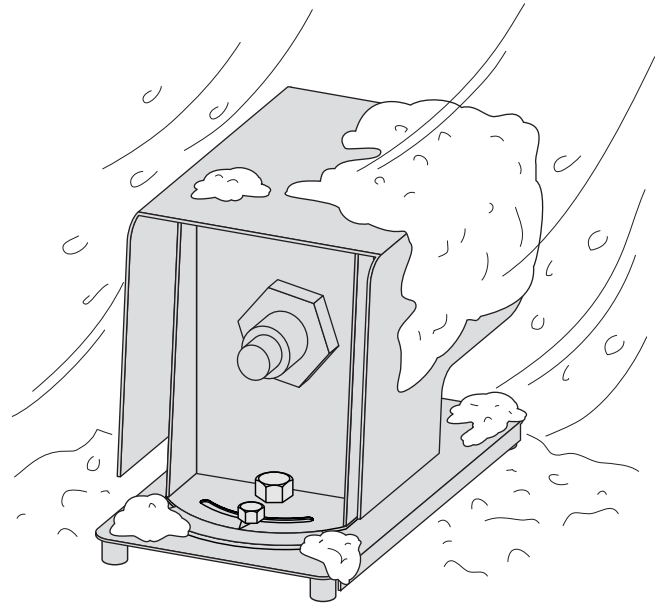
WADECO CO.,LTD.

MICROWAVE SENSOR FOR CRANE CRASH AVOIDANCE

MICRO-ROBO

MWS-CAS-2A/B Micro-Robo is a microwave sensor developed specifically for use on overhead cranes as a crash avoidance sensor.

The sensors are installed face-to-face on adjacent overhead cranes running on the same rails. When one crane approaches the detection area of an adjacent crane, its sensor detects the microwaves transmitted by the sensor mounted on the other crane and an alarm is generated, thus preventing collision.



Reliable detection under all weather conditions.

Features

- **Simple construction**

The transmitter and receiver are combined in one compact and economical unit.

- **Unaffected by adverse environments**

Microwaves are generally unaffected by environmental conditions, thus this sensor is unaffected by rain, wind, snow, frost, heavy dust, smoke or vapor.

- **High penetration**

Easily penetrates dirt and dust accumulation on the antenna, thanks to the high penetrability of microwaves

- **Three dimensional detection area**

The sensor has a conical shaped beam pattern, detection occurs when one sensor enters the detecting area of the others. The detecting area can be adjusted by setting the sensitivity.

- **No set-to-set interference**

Four channels are available, selectable by rotary switch.

This permits the use of multiple Micro-Robos in close proximity to each other.

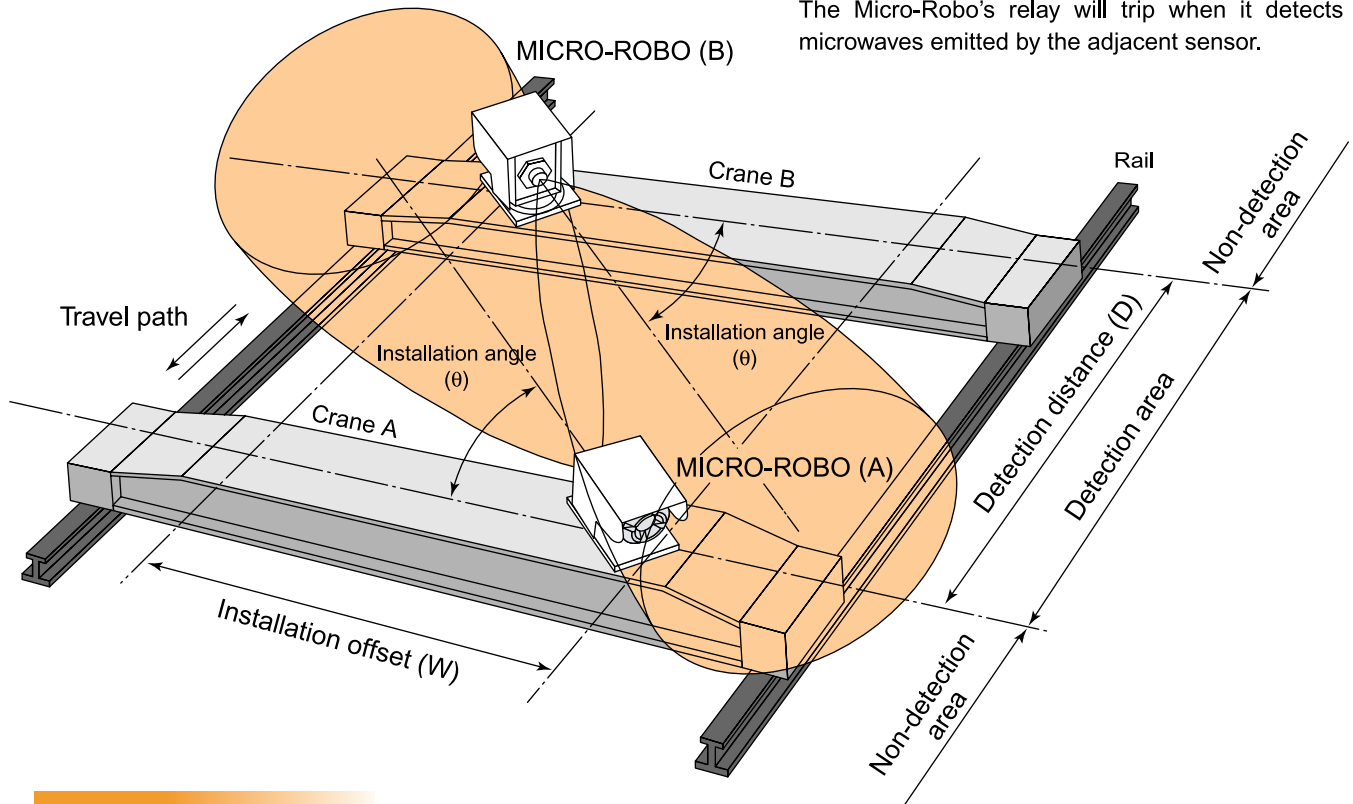
- **Power level & sensitivity indicators**

The received power level and sensitivity-set-point are indicated on the receiver by a bank of 15 LEDs, allowing for easy visual adjustment and maintenance of the sensors.

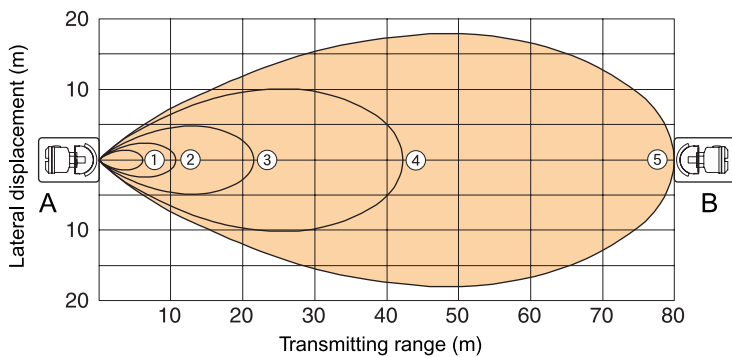
- **Enclosure rating IP65 equivalent**

MICRO-ROBO

Each Micro-Robo transmits and receives microwaves. The Micro-Robo's relay will trip when it detects the microwaves emitted by the adjacent sensor.



Beam pattern and sensitivity



| Beam pattern | Sensitivity |
|--------------|-------------|
| 1 | 5 |
| 2 | 6 |
| 3 | 7 |
| 4 | 8 |
| 5 | 10 |

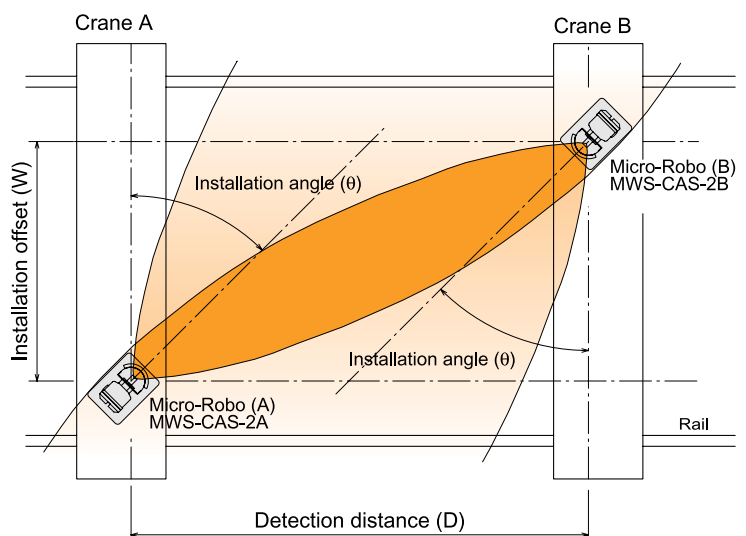
- Micro-Robo A is fixed, Micro-Robo B moves parallel to the face of Micro-Robo A.
- Detection range varies depending on the sensor and circumstances.

Installation

Micro-Robo (A & B) generate alarms when one Micro-Robo approaches the detection area of the other.

The detection distance (D) should be used to determine the installation offset (W) and the installation angle (θ).

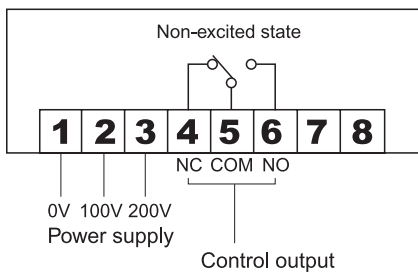
After installation is complete, the installation angle (θ) should be adjusted by loosening the installation angle adjustment bolt. The most desirable installation is obtained by minimizing the installation angle (θ) and maximizing the installation offset (W) for accurate detection.



Specifications

| | |
|--------------------------------------|---|
| Type | MWS-CAS-2A or MWS-CAS-2B |
| Power supply | AC100 ~ 120V or AC200 ~ 240V $\pm 10\%$, 50/60Hz |
| Operating range | 80m/262ft or less |
| Frequency & transmission power | 24GHz approx. Less than 10mW |
| Radiation angle | $\pm 20^\circ$ approx. (angle in half of receiving value) |
| Number of channels | 4 |
| Received power level | Indicated by 1 of 15 LED indicators |
| Sensitivity-set-point | Indicated by 1 of 15 LED indicators |
| Control output | 1C relay contact AC 250V, 3A, $\cos\theta=1$ |
| Delay time from power on to function | Approx. 5sec. |
| Power consumption | 2VA |
| Noise immunity | Pulse noise from noise simulator $\pm 1.5KV$ (normal and common mode) |
| Ambient operating temperature | $-10^\circ C \sim +55^\circ C$ ($14^\circ F \sim 131^\circ F$) |
| Neck rotation angle | $\pm 45^\circ$ |
| Enclosure rating | IP65/NEMA4 equivalent |
| Construction | Base & cover: SS400, Sensor: aluminum diecast |
| Color | Metallic silver grey |
| Weight | 5kg (11lbs) |

Wiring

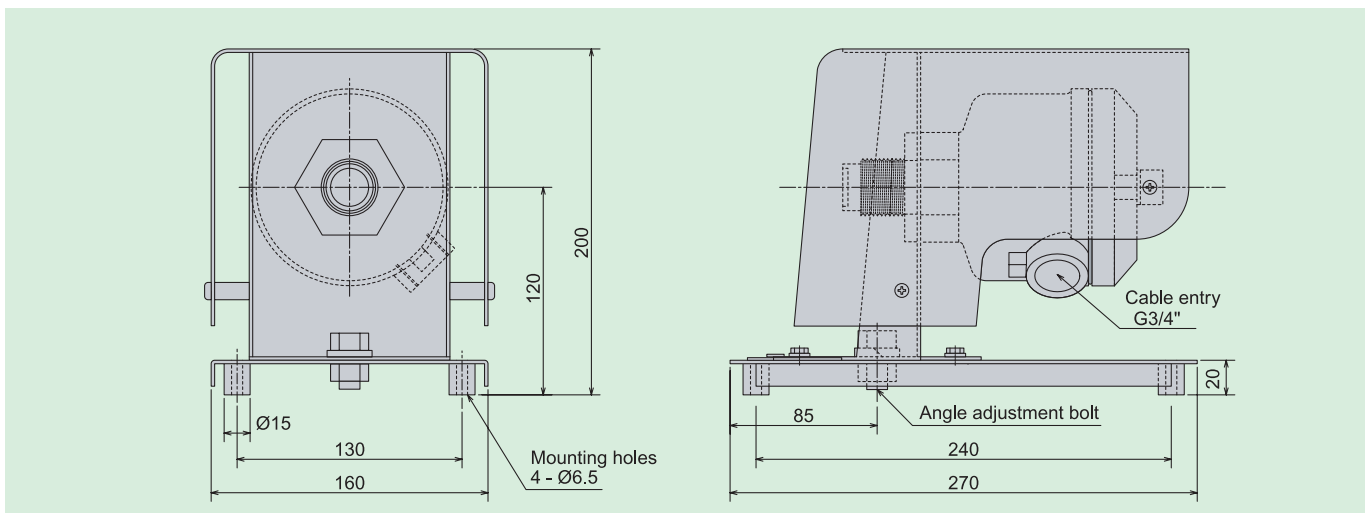


* Phase of power supply must be same from both transmitter and receiver.

Relay configuration

| | | |
|-----------------|---------------------|--------|
| Terminal number | 4 & 5 | 5 & 6 |
| Unpowered state | Closed | Open |
| Powered state | Non-detecting state | Open |
| | Detecting state | Closed |
| | | Closed |
| | | Open |

Dimensions



* Type A & B must be used together in a face-to-face position. A combination of type A & A or type B & B must not be used.

* Do not cut the power of one Micro-Robo unless both cranes are not in operation: they operate as a pair and cutting the power to one will render the other useless.

This specification may be changed without notice.



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